

ON AUTOMORPHISMS OF MATRIX INVARIANTS

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ABSTRACT. Let $Q_{m,n}$ be the space of m -tuples of $n \times n$ -matrices modulo the simultaneous conjugation action of PGL_n . Let $Q_{m,n}(\tau)$ be the set of points of $Q_{m,n}$ of representation type τ . We show that for $m \geq n+1$ the group $\text{Aut}(Q_{m,n})$ of representation type preserving algebraic automorphisms of $Q_{m,n}$ acts transitively on each $Q_{m,n}(\tau)$. Moreover, the action of $\text{Aut}(Q_{m,n})$ on the Zariski open subset $Q_{m,n}(1, n)$ of $Q_{m,n}$ is s -transitive for every positive integer s . We also prove slightly weaker analogues of these results for all $m \geq 3$.

1. INTRODUCTION

Let $M_n(k)^m$ be the set of m -tuples of $n \times n$ -matrices over an algebraically closed field k of characteristic 0. The group $PGL_n(k)$ acts on $M_n(k)^m$ by conjugation. Let $Q_{m,n}$ be the algebraic quotient for this action.

A point x of $Q_{m,n}$ can be lifted to an m -tuple of matrices $(X_1, \dots, X_m) \in M_n(k)$ such that the representation

$$(1) \quad \phi_{ss}(x): k\{u_1, \dots, u_m\} \rightarrow M_k(k), \quad u_i \rightarrow X_i,$$

is semisimple. Moreover, this representation is unique up to equivalence. We say that x has representation type $\tau = (e_1, d_1; \dots; e_r, d_r)$ if $\phi(x)$ is the sum of r irreducible representations ϕ_i of dimension d_i and multiplicity e_i . The set of all points of $Q_{m,n}$ of representation type τ will be denoted by $Q_{m,n}(\tau)$. We remark that $Q_{m,n}(1, n)$ is Zariski open and dense in $Q_{m,n}$. For further details, see §2.

Note that $Q_{m,1}$ is trivially isomorphic to the affine space k^m . In general, however, $Q_{m,n}$ is a very complicated affine variety, both locally and globally.

The local étale structure of $Q_{m,n}$ was studied by Le Bruyn and Procesi [9]. They showed that if $m, n \geq 2$ and $(m, n) \neq (2, 2)$ then $Q_{m,n}(1, n)$ is precisely the smooth locus of $Q_{m,n}$. They also gave a description of the étale neighborhood of a point of Q in terms of representations of quivers; see [9, §§0 and II.1]. The following observation is an immediate consequence of this description.

1.1 Proposition. *Étale neighborhoods of points of the same representation type are isomorphic.*

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Since $Q_{m,n}$ is defined as the quotient of an affine space, it is unirational. Procesi and Formanek showed that $Q_{m,n}$ is rational for $n = 2, 3, 4$; see [11, 4, and 5]. Bessenrodt and LeBruyn [2] proved that $Q_{m,5}$ and $Q_{m,7}$ are stably rational. Katsylo [7] and Schofield [15] showed that $Q_{m,ab}$ is stably birational to $Q_{m,a} \times Q_{m,b}$ if a and b are relatively prime. This, in particular, implies that $Q_{m,n}$ is stably rational whenever n divides 420. The rationality or stable rationality of $Q_{m,n}$ for other values of n is an open problem. For a survey of this problem and related questions we refer the reader to [6 and 8].

The purpose of this paper is to demonstrate that for $m \geq 3$ $Q_{m,n}$ has a very large automorphism group. Let $\text{Aut}(Q_{m,n})$ be the group of algebraic automorphisms of $Q_{m,n}$ which preserve the representation type. Our main results are as follows.

1.2 Theorem. *Let $\tau = (e_1, d_1; \dots; e_r, d_r)$. If $m \geq \max\{d_1, \dots, d_r\} + 1$ then $\text{Aut}(Q_{m,n})$ acts transitively on $Q_{m,n}(\tau)$. In particular, if $m \geq n + 1$ then $\text{Aut}(Q_{m,n})$ acts transitively on every $Q_{m,n}(\tau)$.*

1.3 Theorem. *Let $m \geq n + 1$. Then $\text{Aut}(Q_{m,n})$ acts s -transitively on $Q_{m,n}(1, n)$ for every integer $s \geq 1$.*

Note that if $n = 1$ then $Q_{m,n} = Q_{m,n}(1, n) = k^m$, and Theorem 1.3 says that the group of algebraic automorphisms of k^m acts on k^m s -transitively for any $s \geq 1$; see Theorem 3.1.

We prove slightly weaker analogues of Theorems 1.2 and 1.3 for all $m \geq 3$.

1.4 Theorem. *Let $m \geq 3$. For every representation type τ there is an open $\text{Aut}(Q_{m,n})$ -invariant subset $U_{m,n}(\tau)$ of $Q_{m,n}(\tau)$ on which $\text{Aut}(Q_{m,n})$ acts s -transitively.*

1.5 Theorem. *There exists a nonempty Zariski-open subset $U_{m,n}$ of $Q_{m,n}$ on which $\text{Aut}(Q_{m,n})$ acts s -transitively for every integer $s \geq 1$.*

Theorems 1.2 and 1.4 can be thought of as generalizations of Proposition 1.1. On the other hand, Theorems 1.3 and 1.5 may be viewed as properties of the global geometry of $Q_{m,n}$.

The rest of the paper is structured as follows. In §2 we introduce some notions and results which are used in subsequent sections. In §3 we prove the main theorems for $n = 1$. In §§4 and 5 we discuss a way of constructing elements of $\text{Aut}(Q_{m,n})$ and outline a proof of Theorems 1.2–1.5. The arguments we present there rely on Theorems 4.3 and 4.4 about polynomial equivalence of representations of the free algebra. These results are proved in §§6, 7, and 8.

2. PRELIMINARIES

2.1 Affine quotients. Let G be a reductive group. Given a finite-dimensional representation $G \rightarrow \text{GL}_N(k)$ and a G -invariant affine variety $X \subset k^N$, we define the quotient variety X/G as the spectrum of the ring $k[X]^G$ of G -invariant regular functions on X . The quotient map $\pi: X \rightarrow X/G$ is then induced by the inclusion of rings $k[X]^G \hookrightarrow k[X]$. By a theorem of Hilbert X/G is an affine variety. The quotient map π is the categorical quotient for the G -action on X . That is, any G -equivariant map $f: X \rightarrow T$ into an affine variety T with the trivial G -action factors through a unique morphism $X/G \rightarrow T$; see [10, Theorem 1.1]. Hence, we have the following

2.2 Lemma. Let $F: X \rightarrow Y$ be a G -equivariant morphism of affine varieties. Then F descends to a map of the quotient varieties, i.e. there exists a map $f: X/G \rightarrow Y/G$ such that the diagram

$$\begin{array}{ccc} X & \xrightarrow{F} & Y \\ \pi_X \downarrow & & \downarrow \pi_Y \\ X/G & \xrightarrow{f} & Y/G \end{array}$$

commutes.

We shall be primarily interested in the action of $PGL_n(k)$ on $M_n(k)^m$ given by

$$\begin{aligned} PGL_n(k) \times M_n(k)^m &\rightarrow M_n(k)^m, \\ g(X_1, \dots, X_m) &\rightarrow (g^{-1}X_1g, \dots, g^{-1}X_mg). \end{aligned}$$

The coordinate ring of $M_n(k)^m$ is the polynomial ring $k[x_{ij}^l]$ where x_{ij}^l is the (i, j) -entry of the l th matrix X_l . We shall denote the quotient map for this action by $\pi_{m,n}: (M_n(k))^m \rightarrow Q_{m,n}$. The ring of invariants $C_{m,n} = k[x_{ij}^{(l)}]^{PGL_n}$ is generated by elements of the form $\text{tr}(X_{i_1} \cdots X_{i_n})$; see [17, Theorem 1], [12, Theorem 1.3].

2.3 Representations. Let M be a k -algebra. By a *representation* (resp. an *irreducible representation*) of $k\{u_1, \dots, u_m\}$ in M we mean a k -algebra homomorphism (resp. a surjective k -algebra homomorphism)

$$\rho: k\{u_1, \dots, u_m\} \rightarrow M.$$

Such a representation can be viewed as an m -tuple of elements (resp. generators) of M . If $\rho(u_i) = X_i$ we will write $\rho = (X_1, \dots, X_m)$.

Two representations $\rho_1: k\{u_1, \dots, u_m\} \rightarrow M_1$ and $\rho_2: k\{u_1, \dots, u_m\} \rightarrow M_2$ are said to be *equivalent* if there exists an isomorphism $f: M_1 \rightarrow M_2$ such that $\rho_2 = f \circ \rho_1$. We write $\rho_1 \approx \rho_2$. The direct sum $\rho_1 \oplus \rho_2$ is a representation of $k\{u_1, \dots, u_m\}$ in $M_1 \times M_2$ defined in the obvious way. Up to equivalence, the operation \oplus is commutative and associative. A representation is called *semisimple* if its image is a semisimple k -algebra, i.e. a product of the matrix algebras over k .

2.4 Lemma. For $i = 1, \dots, r$ let ϕ_i be a representation of $k\{u_1, \dots, u_m\}$ in the matrix algebra $M_{d_i}(k)$. Then $\rho = \rho_1 \oplus \cdots \oplus \rho_r$ is irreducible if and only if ρ_1, \dots, ρ_r are irreducible and pairwise inequivalent.

Proof. The lemma is a consequence of [1, Theorem 9.2] and the Chinese Remainder Theorem [14, Lemma 1.7.15]. Q.E.D.

2.5 The representation type. Let $\phi = (X_1, \dots, X_m)$ be a representation of $k\{u_1, \dots, u_m\}$ in the matrix algebra $M_n(k)$. Recall that a strictly increasing sequence of vector subspaces of k^n ,

$$(2) \quad (0) = V_0 \subset V_1 \subset \cdots \subset V_q = k^n$$

is called a *composition series* for ϕ if each V_i is invariant for X_1, \dots, X_m and the induced representations $\phi_i: k\{u_1, \dots, u_m\} \rightarrow \text{End}(V_i/V_{i-1})$ are irreducible

for $i = 1, \dots, q$. The (unordered) sequence of equivalence classes of representations ϕ_1, \dots, ϕ_q of $k\{u_1, \dots, u_m\}$ in matrix algebras is independent of the choice of the composition series. Artin [1] showed that it depends only on $\pi_{m,n}(X_1, \dots, X_m)$ and that, in fact, such sequences (with the dimensions summing up to n) are in bijective correspondence with points of $Q_{m,n}$. In other words, if in some basis of k^n ,

$$\phi = \begin{pmatrix} \phi_1 & & * \\ & \ddots & \\ 0 & & \phi_r \end{pmatrix}$$

with all ϕ_i irreducible then the unordered sequence ϕ_1, \dots, ϕ_q depends only on $x = \pi_{m,n}(X_1, \dots, X_m) \in Q_{m,n}$.

The semisimple representation associated to ϕ (or x) is then defined by

$$(3) \quad \phi_{ss} = \phi_{ss}(x) = \begin{pmatrix} \phi_1 & & 0 \\ & \ddots & \\ 0 & & \phi_r \end{pmatrix}.$$

Let $\phi_{i_1}, \dots, \phi_{i_r}$ be a maximal set of pairwise inequivalent representations among the ϕ_i . If ϕ_{i_j} is of dimension d_j and it occurs e_j times then we define the representation type of x (or ϕ) to be the unordered r -tuple of pairs (e_j, d_j) . We write

$$(4) \quad \tau(x) = \tau(\phi) = \tau(X_1, \dots, X_m) = (e_1, d_1; \dots; e_r, d_r).$$

The associated reduced semisimple representation of x is given by

$$(5) \quad \varphi(x) = \phi_{i_1} \oplus \dots \oplus \phi_{i_r}: k\{u_1, \dots, u_m\} \rightarrow M_{d_1} \times \dots \times M_{d_r}.$$

It is well defined up to equivalence. By Lemma 2.4 $\varphi(x)$ is always irreducible.

An unordered r -tuple of pairs of positive integers $\tau = (e_1, d_1; \dots; e_r, d_r)$ is said to be a representation type (for $n \times n$ -matrices) if $e_1 d_1 + \dots + e_r d_r = n$. There is a partial order on the set of representation types. We can obtain a smaller representation type by subdividing a diagonal block in (3) into two or by declaring two previously inequivalent blocks equivalent. In particular, for any representation type τ we have $(n, 1) \leq \tau \leq (1, n)$. Another equivalent definition, purely in terms of the integers e_i and d_i , is given in [9, §II.1]. See also [13, §7] for a characterization of the representation type in terms of algebras with trace.

The following lemma can be easily derived from either definition.

2.6 Lemma. Let

$$\rho_1: k\{u_1, \dots, u_a\} \rightarrow M_n(k) \quad \text{and} \quad \rho_2: k\{u_1, \dots, u_b\} \rightarrow M_n(k)$$

be representations such that $\rho_1(k\{u_1, \dots, u_a\}) \subset \rho_2(k\{u_1, \dots, u_b\})$. Then $\tau(\rho_1) \leq \tau(\rho_2)$.

We define $Q_{m,n}(\tau)$ to be the set of points $Q_{m,n}$ of representation type τ . The following fact is a consequence of a theorem of Schwarz [16, Lemma 5.5] for affine group actions.

2.7 Theorem (Le Bruyn, Procesi [9, Theorem II.1.1]). *The Zariski closure of $Q_{m,n}(\tau)$ is the union of $Q_{m,n}(\nu)$ taken over all $\nu \leq \tau$. $Q_{m,n}(\tau)$ is irreducible and open in its closure.*

2.8 Corollary. *The set of m -tuples (X_1, \dots, X_m) of $n \times n$ -matrices of representation type $\geq \tau$ is open in $M_n(k)^m$.*

Proof. Denote the set of points of $Q_{m,n}$ of representation type $\geq \tau$ (resp. $\leq \tau$) by $Q_{m,n}(\geq \tau)$ (resp. $Q_{m,n}(\leq \tau)$). By Theorem 2.7 $Q_{m,n}(\leq \nu)$ is closed for every representation type ν . Since there are only finitely many representation types, the set

$$Q_{m,n}(\geq \tau) = Q_{m,n} \setminus \bigcup_{\nu \not\geq \tau} Q_{m,n}(\leq \nu)$$

is open as the complement of a finite union of closed sets. The set we are interested in is the preimage of $Q_{m,n}(\geq \tau)$ under $\pi_{m,n}$. Q.E.D.

2.9 Saturated representations.

2.10 Lemma. *A finite-dimensional semisimple algebra M is generated by two elements.*

Proof. By Lemma 2.4 it is enough to show that there are infinitely many pairwise inequivalent irreducible representations $\rho: k\{u_1, u_2\} \rightarrow M_n(k)$. This follows from Lemma 6.2(a). Q.E.D.

A representation $\rho: k\{u_1, \dots, u_m\} \rightarrow M$ is called *saturated* if $\rho(u_1), \dots, \rho(u_{m-1})$ generate M as a k -algebra.

2.11 Lemma. *For any representation type τ the set of points x whose reduced semisimple representation $\phi(x)$ is saturated, is open in $Q_{m,n}(\tau)$. For $m \geq 3$ this set is nonempty.*

Proof. The nonemptiness assertion is a consequence of Lemma 2.10. Let $F: M_n(k)^m \rightarrow M_n(k)^{m-1}$ be the PGL_n -equivariant map given by $(X_1, \dots, X_m) \rightarrow (X_1, \dots, X_{m-1})$. By Lemma 2.2 this map descends to $f: Q_{m,n} \rightarrow Q_{m-1,n}$. Taking $\rho_1 = (X_1, \dots, X_{m-1})$ and $\rho_2 = (X_1, \dots, X_m)$ in Lemma 2.6 we see that $\tau(f(x)) \leq \tau(x)$ for any $x \in Q_{m,n}$. Hence,

$$fQ_{m,n}(\tau) \subset \bigcup_{\nu \leq \tau} Q_{m-1,n}(\nu),$$

and the set we are interested in is $f^{-1}Q_{m-1,n}(\tau) \cap Q_{m,n}(\tau)$. The lemma now follows from Theorem 2.7. Q.E.D.

3. AUTOMORPHISMS OF k^m

In this section we shall prove Theorems 1.2–1.5 in the case $n = 1$. In this case every point of $Q_{m,1} = M_1(k)^m = k^m$ is of representation type $(1, 1)$, and Theorems 1.2–1.5 reduce to the following.

3.1 Theorem. *For $m \geq 2$ the group $\text{Aut}(k^m)$ of polynomial automorphisms of the affine space k^m acts on k^m s -transitively for positive integer s .*

Note that every automorphism of k^1 is affine, i.e. of the form $x \rightarrow ax + b$. Hence, $\text{Aut}(k^1)$ is 2-transitive but not 3-transitive. We also remark that our proof will work for any infinite base field k .

Proof. Fix s distinct elements c_1, \dots, c_s of the base field k . It is enough to show that for any s -tuple of distinct points $x_1, \dots, x_s \in k^m$ there exists a $g \in \text{Aut}(k^m)$ and a nonzero $e \in k^m$ so that $g(x_i) = c_i e$. Indeed, if $g(x_i) = c_i e$ and $h(y_i) = c_i f$ for some $0 \neq e, f \in k^m$ and $g, h \in \text{Aut}(k^m)$ then $y_i = h^{-1} \circ L \circ g(x_i)$ where L is any linear transformation of k^m taking e to f .

Choose a basis u_1, \dots, u_m for the space of linear forms on k^m so that $u_1(x_i) \neq u_1(x_j)$ for any $1 \leq i < j \leq s$. In this coordinate system $x_i = (x_{1i}, \dots, x_{mi})$ where x_{11}, \dots, x_{1s} are distinct. Thus for any $a_1, \dots, a_s \in k$ there exists a polynomial $f(t)$ in one variable such that $f(x_{1i}) = a_i$ for $i = 1, \dots, s$. In particular, there exist polynomials $f_2(t), \dots, f_m(t)$ such that $f_2(x_{1i}) = c_i - x_{2i}$ and $f_j(x_{1i}) = -x_{ji}$ for $i = 1, \dots, s, j = 3, \dots, m$. Let h_1 be the automorphism of k^m given by

$$\begin{aligned} u_1 &\rightarrow u_1, \\ u_2 &\rightarrow u_2 + f_2(u_1), \\ &\vdots \\ u_m &\rightarrow u_m + f_m(u_1). \end{aligned}$$

Then $h_1(x_i) = (x_{1i}, c_i, 0, 0, \dots, 0)$ for $i = 1, \dots, s$. Now let h_2 be the automorphism of k^m given by

$$\begin{aligned} u_1 &\rightarrow u_1 - f(u_2), \\ u_2 &\rightarrow u_2, \\ &\vdots \\ u_m &\rightarrow u_m, \end{aligned}$$

where $f(c_i) = x_{1i}$ for $i = 1, \dots, n$. Then for $i = 1, \dots, s, h_2 \circ h_1(x_i) = (0, c_i, 0, \dots, 0)$, as desired. Q.E.D.

Theorem 3.1 has the following algebraic formulation. Let $M = k \times \dots \times k$ (s times) and let ρ_1 and $\rho_2: k[x_1, \dots, x_m] \rightarrow M$ be surjective k -algebra homomorphisms. Then there exists an automorphism of the polynomial algebra $\sigma: k[x_1, \dots, x_m] \rightarrow k[x_1, \dots, x_m]$ such that $\rho_2 = \rho_1 \circ \sigma$.

Observe that in the above statement we can replace the commutative polynomial algebra $k[x_1, \dots, x_m]$ by the noncommutative polynomial algebra $k\{u_1, \dots, u_m\}$; our proof will work without any changes. We record these observations below.

3.2 Definition. Let M be a k -algebra and let ρ_1 and $\rho_2: k\{u_1, \dots, u_m\} \rightarrow M$ be representations. We say that ρ_1 and ρ_2 are polynomially equivalent if there exists an automorphism $\sigma: k\{u_1, \dots, u_m\} \rightarrow k\{u_1, \dots, u_m\}$ such that $\rho_2 = \rho_1 \circ \sigma$.

Since a representation of $k\{u_1, \dots, u_m\}$ in M uniquely determines an m -tuple of elements in M and vice versa, we shall also speak of polynomial equivalence m -tuples of elements of M .

3.3 Proposition. If $s \geq 1$ and $m \geq 2$ then any two irreducible representations of $k\{u_1, \dots, u_m\}$ in $k \times \dots \times k$ (s times) are polynomially equivalent.

3.4 Remark. In practice we shall only work with so-called tame automorphisms, i.e. compositions of linear automorphisms of $k\{u_1, \dots, u_m\}$ and

automorphisms of the form

$$(6) \quad \begin{aligned} u_1 &\rightarrow u_1, \\ &\vdots \\ u_i &\rightarrow au_i + p(u_1, \dots, u_{i-1}, u_{i+1}, \dots, u_m), \\ &\vdots \\ u_m &\rightarrow u_m, \end{aligned}$$

where $a \neq 0$ and p is a polynomial in $m - 1$ variables. For $m \geq 3$ it is not known whether or not every element of $\text{Aut}(k\{u_1, \dots, u_m\})$ is tame; see [3, §4]. The difference between $\text{Aut}(k\{u_1, \dots, u_m\})$ and its subgroup of tame automorphisms $\text{TAut}(k\{u_1, \dots, u_m\})$ shall not concern us here. In fact, one could replace $\text{Aut}(k\{u_1, \dots, u_m\})$ by $\text{TAut}(k\{u_1, \dots, u_m\})$ everywhere in this paper; all of our results would remain true and all of our arguments would go through unchanged. The same applies to $\text{Aut}(k^m)$ versus $\text{TAut}(k^m)$ in the statement of Theorem 3.1.

4. PROOFS OF THEOREMS 1.2–1.4

As we observed in the previous section, the automorphisms of $k^m = Q_{m,1}$ constructed in the proof of Theorem 3.1 are all induced by automorphisms of $k\{u_1, \dots, u_m\}$. We shall now show that elements of $\text{Aut}(Q_{m,n})$ can be constructed from automorphisms of $k\{u_1, \dots, u_m\}$ for any n .

For $\sigma \in \text{End}(k\{u_1, \dots, u_m\})$ we define σ^* by

$$(7) \quad \begin{aligned} \sigma^* &: M_n(k)^m \rightarrow M_n(k)^m, \\ (X_1, \dots, X_m) &\rightarrow (\sigma(u_1)(X), \dots, \sigma(u_m)(X)). \end{aligned}$$

4.1 Proposition. *Every $\sigma \in \text{End}(k\{u_1, \dots, u_m\})$ induces an algebraic morphism $\sigma_*: Q_{m,n} \rightarrow Q_{m,n}$ such that the following diagram is commutative.*

$$\begin{array}{ccc} M_n(k)^m & \xrightarrow{\sigma^*} & M_n(k)^m \\ \pi_{m,n} \downarrow & & \downarrow \pi_{m,n} \\ Q_{m,n} & \xrightarrow{\sigma_*} & Q_{m,n} \end{array}$$

Moreover, if σ is an automorphism of $k\{u_1, \dots, u_m\}$ then σ_* is a representation type preserving automorphism of $Q_{m,n}$.

Proof. Since σ^* is PGL_n -invariant, the existence and uniqueness of σ_* follows from Lemma 2.2. By uniqueness,

$$(\sigma_1 \circ \sigma_2)_* = (\sigma_1)_* \circ (\sigma_2)_*$$

and

$$(\text{id})_* = \text{id}: Q_{m,n} \rightarrow Q_{m,n}.$$

Thus if σ is an automorphism of $k\{u_1, \dots, u_m\}$ then σ_* is an automorphism of $Q_{m,n}$.

It remains to show that for $\sigma \in \text{Aut}(k\{u_1, \dots, u_m\})$, σ_* preserves the representation type, i.e. for any $x \in Q_{m,n}$

$$(8) \quad \tau(\sigma_*x) = \tau(x).$$

For any $\sigma \in \text{End}(k\{u_1, \dots, u_m\})$ the subalgebra of $M_n(k)^m$ generated by X_1, \dots, X_m contains the subalgebra generated by Y_1, \dots, Y_m where

$$(X_1, \dots, X_m) = \sigma^*(Y_1, \dots, Y_m).$$

Hence, for any $x \in C$ we have $\tau(\sigma_*(x)) \leq \tau(x)$; see Lemma 2.6. When σ is an automorphism, this yields (8). Q.E.D.

As a direct corollary of our definition, σ_* has the following property.

4.2 Lemma. *Let σ be an automorphism of $k\{u_1, \dots, u_m\}$, let x and y be points of $Q_{m,n}(\tau)$ let $\varphi(x)$ and $\varphi(y)$ be their reduced semisimple representations; see (5). Then $\sigma_*(x) = y$ if and only if $\varphi(x) \circ \sigma \approx \varphi(y)$.*

Proposition 4.1 says that $\text{Aut}(k\{u_1, \dots, u_m\}) \rightarrow \text{Aut}(Q_{m,n})$ is a morphism of groups. We shall prove Theorems 1.2–1.5 by demonstrating that the image of this map is already big enough to have the required transitivity properties. In order to do this we will need the following generalizations of Proposition 3.3.

Recall that a representation $\rho: k\{u_1, \dots, u_m\} \rightarrow M$ is saturated if $\rho(u_1), \dots, \rho(u_{m-1})$ generate M as a k -algebra.

4.3 Theorem. *Let M be a finite-dimensional semisimple k -algebra and let $m \geq 3$. Then any two saturated representations of $k\{u_1, \dots, u_m\}$ in M are polynomially equivalent.*

4.4 Theorem. *Let M be a semisimple algebra,*

$$(9) \quad M = M_{d_1}(k) \times \dots \times M_{d_r}(k)$$

and let $m \geq \max\{d_1, \dots, d_r\} + 1$. Then any two irreducible representations of $k\{u_1, \dots, u_m\}$ in M are polynomially equivalent.

We shall defer the proofs of these theorems to §§6, 7 and 8. In the remainder of this section we will demonstrate how Theorems 1.2, 1.3 and 1.4 can be derived from Theorems 4.3 and 4.4. In order to do this in the case of Theorem 1.5 we need a more elaborate argument which will be presented in the next section.

Proof of Theorem 1.2. Let $\tau = (e_1, d_1; \dots; e_r, d_r)$ be a representation type and let M be as in (9). Choose x and y in $Q_{m,n}(\tau)$. As we observed in 2.5, the reduced semisimple representations $\varphi(x)$ and $\varphi(y): k\{u_1, \dots, u_m\} \rightarrow M$ are irreducible. Hence, by Theorem 4.4 they are polynomially equivalent, i.e. $\varphi(y) = \varphi(x) \circ \sigma$. By Lemma 4.2 this implies $\sigma_*x = y$, as desired. Q.E.D.

Proof of Theorem 1.4. Let U_0 be the set of points x in $Q_{m,n}(\tau)$ such that $\varphi(x)$ is saturated. By Lemma 2.11 U_0 is a nonempty Zariski-open subset of $Q_{m,n}(\tau)$ (here we use the assumption that $m \geq 3$!). Let $x, y \in U_0$. By Theorem 4.3 $\varphi(x)$ and $\varphi(y)$ are polynomially equivalent, i.e. $\varphi(y) = \varphi(x) \circ \sigma$ for some $\sigma \in \text{Aut}(k\{u_1, \dots, u_m\})$. By Lemma 4.2 $\sigma_*(x) = y$. Thus $\text{Aut}(Q_{m,n})$ acts transitively on U_0 . Unfortunately, U_0 is not $\text{Aut}(Q_{m,n})$ -invariant. This problem, however, can be corrected by defining $U_{m,n}(\tau)$ as the union of gU_0 over all g in $\text{Aut}(Q_{m,n})$. Q.E.D.

Proof of Theorem 1.3. We use a diagonal argument. Let x_1, \dots, x_s and y_1, \dots, y_s be two m -tuples of distinct elements of $Q_{m,n}(1, n)$. Denote their associated irreducible representations by $\varphi(x_1), \dots, \varphi(x_s)$ and $\varphi(y_1), \dots, \varphi(y_s)$:

$k\{u_1, \dots, u_m\} \rightarrow M_n(k)$ respectively. By our assumption $\varphi(x_i) \not\approx \varphi(x_j)$ and $\varphi(y_i) \not\approx \varphi(y_j)$ for $i \neq j$. Then by Lemma 2.4,

$$(10) \quad \rho_x = \varphi(x_1) \oplus \dots \oplus \varphi(x_s) \quad \text{and} \quad \rho_y = \varphi(y_1) \oplus \dots \oplus \varphi(y_s)$$

are irreducible representations of $k\{u_1, \dots, u_m\}$ in $M_n(k) \times \dots \times M_n(k)$ (s times). By Theorem 4.4 $\rho_y = \rho_x \circ \sigma$ for some $\sigma \in \text{Aut}(k\{u_1, \dots, u_m\})$. Then for $i = 1, \dots, s$ $\varphi(x_i) = \varphi(y_i) \circ \sigma$, and hence by Lemma 4.2, $\sigma_*(x_i) = y_i$. Q.E.D.

5. PROOF OF THEOREM 1.5

Let $U_{m,n}$ be the set of points $x \in Q_{m,n}(1, n)$ such that the associated irreducible representation $\varphi(x)$ is saturated. By Lemma 2.11 this set is Zariski-open and nonempty when $m \geq 3$. We are going to prove that it has the property claimed in the statement of Theorem 1.5.

Let x_1, \dots, x_s and y_1, \dots, y_s be two m -tuples of distinct elements of U and let ρ_x and ρ_y be as in (10). It is sufficient to prove that ρ_x and ρ_y are polynomially equivalent; as we saw in the proof of Theorem 1.3 $\rho_y = \rho_x \circ \sigma$ implies $y_i = \sigma_*(x_i)$ for $i = 1, \dots, s$. The polynomial equivalence of ρ_x and ρ_y , however, does not follow directly from Theorem 4.3. Indeed, while the representations $\varphi(x_1), \dots, \varphi(x_s)$ are pairwise inequivalent, their restrictions to $k\{u_1, \dots, u_{m-1}\}$ do not need to be. If they are not then ρ_x will not be saturated, and Theorem 4.3 will not apply. The situation is saved by Proposition 5.1 below. This proposition says that we can choose α and β in $\text{Aut}(k\{u_1, \dots, u_m\})$ such that

- (i) $\varphi(x_i) \circ \alpha$ and $\varphi(y_i) \circ \beta$ are saturated for $i = 1, \dots, s$,
- (ii) the restrictions of $\varphi(x_i) \circ \alpha$ to $k\{u_1, \dots, u_{m-1}\}$ are pairwise inequivalent,
- (iii) the restrictions of $\varphi(y_i) \circ \beta$ to $k\{u_1, \dots, u_{m-1}\}$ are pairwise inequivalent.

By Lemma 2.4 $\rho_x \circ \alpha$ and $\rho_y \circ \beta$ are saturated representations of $k\{u_1, \dots, u_m\}$ in $M_n(k) \times \dots \times M_n(k)$ (s times). By Theorem 4.3 $\rho_x \circ \alpha$ and $\rho_y \circ \beta$ are polynomially equivalent. Since polynomial equivalence is a transitive relation, this implies that ρ_x and ρ_y are polynomially equivalent, thus proving Theorem 1.5.

5.1 Proposition. *For $i = 1, \dots, s$ let ϕ_i be a saturated representation of $k\{u_1, \dots, u_m\}$ in $M_d(k)$. Assume that ϕ_1, \dots, ϕ_s are pairwise inequivalent. Then there exists a $\sigma \in \text{Aut}(k\{u_1, \dots, u_m\})$ such that*

- (i) $\phi_i \circ \sigma$ is saturated for $i = 1, \dots, s$ and
- (ii) the restrictions of $\phi_i \circ \sigma$ to $k\{u_1, \dots, u_{m-1}\}$ are pairwise inequivalent.

Proof. Denote the restriction of a representation ρ to $k\{u_1, \dots, u_{m-1}\}$ by $r(\rho)$. Let $S(\phi_1, \dots, \phi_s)$ be the set of pairs (i, j) such that $i \neq j$ and $r(\phi_i) \approx r(\phi_j)$. Without loss of generality we can make the following minimality assumption on ϕ_1, \dots, ϕ_s .

Minimality Assumption. For any $\sigma \in \text{Aut}(k\{u_1, \dots, u_m\})$ such that each $\phi_i \circ \sigma$ is saturated $|S(\phi_1, \dots, \phi_s)| \leq |S(\phi_1 \circ \sigma, \dots, \phi_s \circ \sigma)|$.

Since the representations $r(\phi_i)$ are irreducible, $r(\phi_i) \approx r(\phi_j)$ if and only if $d_i = d_j$ and ϕ_i, ϕ_j map to the same point in Q_{m-1, d_i} . Hence,

$$S(\phi_1 \circ \sigma, \dots, \phi_s \circ \sigma) = S(\phi_1, \dots, \phi_s)$$

for σ “close” to the identity automorphism of $k\{u_1, \dots, u_m\}$.

5.2 Lemma. *If $(a, b) \in S(\phi_1, \dots, \phi_s)$ then for every $w \geq 1$,*

$$\mathrm{Tr} \phi_a(u_m^w) = \mathrm{Tr} \phi_b(u_m^w).$$

Proof. Assume the lemma fails for some $w \geq 1$. Define σ by

$$u_1 \rightarrow u_1 + cu_m^w$$

$$u_2 \rightarrow u_2$$

$$\vdots$$

$$u_m \rightarrow u_m.$$

Then for a generic choice of $c \in k$, $r(\phi_i \circ \sigma) \not\approx r(\phi_j \circ \sigma)$ whenever $(i, j) \notin S(\phi_1, \dots, \phi_s)$ and every $\phi_i \circ \sigma$ will remain saturated. Moreover, when $c \neq 0$ $r(\phi_a \circ \sigma) \not\approx r(\phi_b \circ \sigma)$, since $\mathrm{Tr} \phi_a \circ \sigma(u_1^w) \neq \mathrm{Tr} \phi_b \circ \sigma(u_1^w)$. This means that

$$S(\phi_1 \circ \sigma, \dots, \phi_s \circ \sigma) \subset S(\phi_1, \dots, \phi_s) \setminus \{(a, b)\},$$

contradicting our minimality assumption. Q.E.D.

5.3 Lemma. *If $(a, b) \in S(\phi_1, \dots, \phi_s)$ then $\mathrm{Tr} \phi_a(u_m p) \neq \mathrm{Tr} \phi_b(u_m p)$ for some $p \in k\{u_1, \dots, u_{m-1}\}$.*

Proof. By our assumption $d_a = d_b$ and there exists an invertible $d_a \times d_a$ -matrix g such that $\phi_b(u_i) = g^{-1} \phi_a(u_i) g$ for $i = 1, \dots, m-1$. Since ϕ_a and ϕ_b are not equivalent, $\phi_a(u_m) \neq g^{-1} \phi_b(u_m) g$. Recall that the Killing bilinear form $(x, y) = \mathrm{Tr}(xy)$ is nonsingular on $M_{d_a}(k)$. Therefore, there exists an $H \in M_{d_a}(k)$ such that $\mathrm{Tr}(\phi_b(u_m) H) \neq \mathrm{Tr}(g^{-1} \phi_a(u_m) g H)$. Since ϕ_b is saturated, we can write H as $\phi_b(p)$ for some $p \in k\{u_1, \dots, u_{m-1}\}$. By our assumption $H = \phi_b(p) = g^{-1} \phi_a(p) g$. Thus

$$\begin{aligned} \mathrm{Tr} \phi_b(u_m p) &= \mathrm{Tr} \phi_b(u_m) H \neq \mathrm{Tr} g^{-1} \phi_a(u_m) g H \\ &= \mathrm{Tr} g^{-1} \phi_a(u_m) g g^{-1} \phi_a(p) g = \mathrm{Tr} \phi_a(u_m p), \end{aligned}$$

as desired. Q.E.D.

We can now finish the proof of Proposition 5.1. Assume that the Proposition fails, i.e. $S(\phi_1, \dots, \phi_s) \neq \emptyset$. Let

$$(a, b) \in S(\phi_1, \dots, \phi_s).$$

Choose $p(u_1, \dots, u_{m-1})$ as in Lemma 5.3 and let σ be the automorphism of $k\{u_1, \dots, u_m\}$ given by

$$u_1 \rightarrow u_1,$$

$$\vdots$$

$$u_{m-1} \rightarrow u_{m-1},$$

$$u_m \rightarrow u_m + p(u_1, \dots, u_{m-1}).$$

Since $r(\phi_i \circ \sigma) = r(\phi_i)$ for $i = 1, \dots, s$,

(i) $\phi_i \circ \sigma$ is saturated of $i = 1, \dots, s$ and

(ii) $S(\phi_1 \circ \sigma, \dots, \phi_s \circ \sigma) = S(\phi_1, \dots, \phi_s)$.

Hence, $\phi_1 \circ \sigma, \dots, \phi_s \circ \sigma$ satisfy our minimality assumption. On the other hand,

(iii) By Lemma 5.2 $\text{Tr } \phi_a(u_m^w) = \text{Tr } \phi_b(u_m^w)$ for any positive integer w . We will use this below with $w = 2$.

(iv) $\text{Tr } \phi_a(q) = \text{Tr } \phi_b(q)$ for any $q \in k\{u_1, \dots, u_{m-1}\}$ because $(a, b) \in S(\phi_1, \dots, \phi_s)$. We will use this below with $q = p^2$.

(iv) By Lemma 5.2 applied to $\phi_1 \circ \sigma, \dots, \phi_s \circ \sigma$, $\text{Tr } \phi_a \circ \sigma(u_m^w) = \text{Tr } \phi_b \circ \sigma(u_m^w)$ for any positive integer w . We will use this below with $w = 2$.

Putting (iii), (iv) and (v) together, we obtain

$$\begin{aligned} 2\text{Tr } \phi_a(u_m p) &= \text{Tr } \phi_a \circ \sigma(u_m^2) - \text{Tr } \phi_a(p^2) - \text{Tr } \phi_a(u_m^2) \\ &= \text{Tr } \phi_b \circ \sigma(u_m^2) - \text{Tr } \phi_b(p^2) - \text{Tr } \phi_b(u_m^2) = 2\text{Tr } \phi_b(u_m p), \end{aligned}$$

contradicting our choice of p . Q.E.D.

6. POLYNOMIAL EQUIVALENCE OF SATURATED REPRESENTATIONS

We now turn to the proof of Theorem 4.3. Let $\text{Gr}(d)$ be the disjoint union of all grassmannians $\text{Gr}(l, d)$ for $l = 1, \dots, d-1$. For $d \times d$ -matrices X_1, \dots, X_s we define $V(X_1, \dots, X_s)$ to be the subvariety of $\text{Gr}(d)$ consisting of all subspaces of k^d simultaneously invariant under the action of X_1, \dots, X_s . Recall that by Burnside's theorem X_1, \dots, X_s generate $M_d(k)$ if and only if $V(X_1, \dots, X_s) = \emptyset$.

6.1 Proposition. *Suppose X_1, \dots, X_m generate $M_d(k)$. Let W be a subvariety of $\text{Gr}(d)$ of dimension e . Then for s generic linear combinations Y_1, \dots, Y_s of X_1, \dots, X_m ,*

$$\dim V(Y_1, \dots, Y_s) \cap W \leq e - s.$$

Here as usual, $\dim \emptyset = -\infty$. In particular, for $e+1$ generic linear combinations Y_1, \dots, Y_{e+1} of X_1, \dots, X_m we have $V(Y_1, \dots, Y_{e+1}) \cap W = \emptyset$.

Proof. It is enough to show that if $Y = a_1 X_1 + \dots + a_m X_m$ then

$$(11) \quad \dim V(Y) \cap W \leq \dim W - 1$$

for a generic choice of a_1, \dots, a_m .

Choose a finite collection of points $w_1, \dots, w_N \in W$ such that there is at least one in each irreducible component. Since X_1, \dots, X_m have no common invariant subspaces in k^d , for each w_i there is an X_j which does not preserve it. Hence, a generic linear combination of X_1, \dots, X_m does not preserve any w_i . In other words, for a generic choice of a_1, \dots, a_m ,

$$w_1, \dots, w_N \notin V(Y)$$

which immediately implies the inequality (11). Q.E.D.

Let $M = M_{d_1}(k) \times \dots \times M_{d_r}(k)$. In the sequel we will think of elements of M as block-diagonal matrices of size $d_1 + \dots + d_r$.

6.2 Lemma. (a) Suppose X_1, \dots, X_m generate $M_d(k)$. Assume that X_1 has distinct eigenvalues. Then for a generic choice of a_2, \dots, a_m , the two matrices X_1 and $Y = a_1X_1 + \dots + a_mX_m$ generate $M_d(k)$.

(b) Suppose X_1, \dots, X_m generate $M = M_{d_1}(k) \times \dots \times M_{d_r}(k)$. Assume that X_1 has distinct eigenvalues. Then for a generic choice of a_2, \dots, a_m , the two elements X_1 and $Y = a_1X_1 + \dots + a_mX_m$ generate M .

Proof. A matrix with distinct eigenvalues has only finitely many invariant subspaces. That is, $W = V(X_1)$ is zero-dimensional. Proposition 6.1 says that for a generic choice of the $a_i - s$, $V(X_1) \cap V(Y) = \emptyset$. This proves part (a). Part (b) follows from (a) and Lemma 2.4. Q.E.D.

We are now ready to finish the proof of Theorem 4.3. The remaining part of the argument is just a more elaborate version of our proof of Theorem 3.1. Let M be as in (9).

Choose r diagonal matrices A_1, \dots, A_r such that $A_j \in M_{d_j}$, each A_j has distinct eigenvalues, and A_j and A_l have no common eigenvalues when $j \neq l$. Let

$$A = \begin{pmatrix} A_1 & & 0 \\ & \ddots & \\ 0 & & A_r \end{pmatrix}.$$

Now choose $B \in M$ so that A and B generate M . This can be done, for example, by following the recipe of Proposition 6.2(b).

Let $\rho = (X_1, \dots, X_m)$ be a saturated representation of $k\{u_1, \dots, u_m\}$ in M . In order to prove Theorem 4.3 it is enough to show that ρ is polynomially equivalent to $(A, B, 0, \dots, 0)$. We shall do this in five steps.

Step 1. We may assume without loss of generality that $X_m = A$.

Proof. Since ρ is saturated, there exists a $p \in k\{u_1, \dots, u_{m-1}\}$ such that $\rho(p) = A - X_m$. Applying the automorphism

$$\begin{aligned} u_1 &\rightarrow u_1, \\ &\vdots \\ u_{m-1} &\rightarrow u_{m-1}, \\ u_m &\rightarrow u_m + p(u_1, \dots, u_{m-1}) \end{aligned}$$

we see that ρ is polynomially equivalent to (X_1, \dots, X_{m-1}, A) . Q.E.D.

Step 2. We may assume without loss of generality that $X_m = A$ and X_{m-1}, X_m generate $M_n(k)$.

Proof. By the result of Step 1 we may assume that $X_m = A$. Let $Y = a_1X_1 + \dots + a_mX_m$. When $a_{m-1} \neq 0$, $\rho = (X_1, \dots, X_m)$ is polynomially equivalent to $(X_1, \dots, X_{m-2}, Y, X_m)$. By Lemma 6.2(b) Y and $X_m = A$ generate M for a generic choice of the coefficients $a_i \in k$. Q.E.D.

Step 3. We may assume without loss of generality that $X_m = A$ and $X_1 = B$.

Proof. We begin with (X_1, \dots, X_m) as in Step 2. Choose a polynomial q in two variables so that $q(X_{m-1}, A) = B - X_1$. After replacing X_1 by $X_1 + q(X_{m-1}, X_m)$ (here we use the assumption that $m \geq 3$!) we will obtain an

m -tuple polynomially equivalent to the original one, with $X_1 = B$ and $X_m = A$. Q.E.D.

Step 4. We may assume without loss of generality that $X_1 = A$ and $X_2 = B$.

Proof. Permuting X_1, \dots, X_m produces a polynomially equivalent m -tuple. Q.E.D.

Step 5. (X_1, \dots, X_m) is polynomially equivalent to $(A, B, 0, \dots, 0)$.

Proof. Since A and B generate M , for each $i = 3, \dots, m$, there exists a $p_i \in k\{u_1, u_2\}$ such that $p_i(A, B) = X_i$. Applying the automorphism

$$\begin{aligned} u_1 &\rightarrow u_1, \\ u_2 &\rightarrow u_2, \\ u_3 &\rightarrow u_3 - p_3(u_1, u_2), \\ &\vdots \\ u_m &\rightarrow u_m - p_m(u_1, u_2) \end{aligned}$$

we arrive at the m -tuple $(A, B, 0, \dots, 0)$. Q.E.D.

7. IRREDUCIBLE SUBSPACES

The remainder of this paper will be devoted to proving Theorem 4.4. When $m = 2$ the theorem reduces to Proposition 3.3. Therefore, from now on we shall assume that m is at least 3.

We begin by observing that for $m \geq \dim_k(M)$ Theorem 4.4 is an easy consequence of Theorem 4.3. Indeed, it is enough to show that an arbitrary irreducible representation $\rho = (X_1, \dots, X_m): k\{u_1, \dots, u_m\} \rightarrow M$ is polynomially equivalent to a saturated one. Since X_1, \dots, X_m are linearly dependent, we may assume (after permuting them if necessary) that X_m is a linear combination of X_1, \dots, X_{m-1} . Then X_1, \dots, X_{m-1} generate M , as desired.

If $M = M_n(k)$, we can do a little better by applying Proposition 6.1 with $W = \text{Gr}(n)$. The dimension of $\text{Gr}(n)$ is $[n^2/4]$ where $[n^2/4]$ denotes the integral part of $n^2/4$. For $m > [n^2/4] + 1$, Proposition 6.1 says that after a linear change of variables we may assume that $V(X_1, \dots, X_{m-1}) = \emptyset$. In other words, (X_1, \dots, X_m) is saturated, and we can apply Theorem 4.3. This proves Theorem 4.4 in the case $M = M_n(k)$ and $m \geq [n^2/4] + 2$. Our proof of Theorem 4.4 in the general case is based on a more careful argument along these lines. The main improvement will be a better choice of W in the application of Proposition 6.1. Instead of trying to eliminate all invariant subspaces of X_1, \dots, X_{m-1} we shall only focus on the irreducible ones; see the proof of Proposition 8.3. In the remainder of this section we shall discuss some of the properties of irreducible subspaces for a given representation ϕ .

Let $\phi: k\{u_1, \dots, u_l\} \rightarrow M_n(k)$ be a representation and let

$$(12) \quad (0) = V_0 \subset V_1 \subset \dots \subset V_q = k^n$$

be a composition series of ϕ as in (2). Denote the induced irreducible representations of $k\{u_1, \dots, u_l\} \rightarrow \text{End}(V_i/V_{i-1})$ by ϕ_i .

We say that an invariant subspace $U \subset k^n$ is *irreducible* for ϕ if the induced representation $k\{u_1, \dots, u_l\} \rightarrow \text{End}(U)$ is irreducible, i.e. U is irreducible as a $k\{u_1, \dots, u_l\}$ -module with the module structure given by ϕ .

Let $\alpha: k\{u_1, \dots, u_l\} \rightarrow M_d(k)$ be an irreducible representation. Denote the d -dimensional vector space on which $M_d(k)$ operates by U_α . We view U_α as a $k\{u_1, \dots, u_l\}$ -module via α . Let $H_\alpha = \text{Hom}_{k\{u\}}(U_\alpha, k^n)$ be the set of all $k\{u_1, \dots, u_l\}$ -homomorphisms from U_α to k^n with the $k\{u_1, \dots, u_l\}$ -module structure on k^n given by ϕ . We will think of H_α as a k -vector space. In this situation Schur's lemma can be restated as follows.

7.1 Lemma. (a) Let $0 \neq f \in H_\alpha$. Then the image of f is an irreducible d -dimensional subspace of k^n .

(b) Let $f, g: U_\alpha \rightarrow W$ be two homomorphisms of $k\{u_1, \dots, u_l\}$ -modules. Assume that $f(U_\alpha) = g(U_\alpha)$. Then $f = cg$ for some $c \in k$.

Proof. (a) Since U_α is irreducible as a $k\{u_1, \dots, u_l\}$ -module, so is $f(U_\alpha)$. Since $\ker(f)$ is a $k\{u_1, \dots, u_l\}$ -submodule of U_α , it is either (0) or all of U_α . The case $\ker(f) = U_\alpha$ is ruled out by the assumption that $f \neq 0$. This proves part (a). To prove (b) observe that if $f(U_\alpha) = g(U_\alpha)$ then

$$f^{-1} \circ g: U_\alpha \rightarrow U_\alpha$$

is an endomorphism of U_α as a $k\{u_1, \dots, u_l\}$ -module. By Schur's lemma any such endomorphism is a scalar multiplication. Q.E.D.

Let U be an irreducible subspace of k^n . Then $U \cap V_i$ is either (0) or all of U . The smallest value of i such that $U \subset V_i$ will be called *the level* of U . We will say that $f \in H_\alpha$ is of level i if $f(U_\alpha)$ is of level i .

7.2 Lemma. Let U be an irreducible subspace of k^n of level i . Then

(a) U is isomorphic to V_i/V_{i-1} as a $k\{u_1, \dots, u_l\}$ -module.

(b) The representation $k\{u_1, \dots, u_l\} \rightarrow \text{End}(U)$ induced by ϕ is equivalent to ϕ_i .

(c) There exists an $f \in H_{\phi_i}$ such that $f(U_{\phi_i}) = U$.

Proof. Since U is of level i , $U \subset V_i$ and the projection map $U \rightarrow V_i/V_{i-1}$ is an injective homomorphism of irreducible $k\{u_1, \dots, u_l\}$ -modules. Hence, it must be an isomorphism. Parts (b) and (c) are immediate consequences of (a). Q.E.D.

7.3 Lemma. Let f_1, \dots, f_e be nonzero elements of H_α of levels $1 \leq i_1 < \dots < i_e \leq q$. Then

(a) f_1, \dots, f_e are linearly independent over k .

(b) Assume that there are no elements of H_α of any other level. Then f_1, \dots, f_e form a basis of H_α .

Proof. (a) Suppose $a_1 f_1 + \dots + a_e f_e = 0$. By Lemma 7.1 $f_e: U_\alpha \rightarrow k^n$ is injective and $f_e(U_\alpha)$ is irreducible. Hence, $f_e(U_\alpha) \cap V_{i_e-1} = (0)$ and for any $0 \neq u \in U_\alpha$ we have $f_e(u) \notin V_{i_e}$ while $f_1(u), \dots, f_{e-1}(u) \in V_{i_e-1}$. This is only possible if $a_e = 0$. Part (a) now follows by induction on e .

(b) Let f be of level i_j . Composing f (resp. f_j) with the projection map $V_i \rightarrow V_i/V_{i-1}$ we obtain \tilde{f} (resp. \tilde{f}_j): $U_\alpha \rightarrow V_{i_j}/V_{i_j-1}$. Since both of these maps are surjective, Lemma 7.1(b) says that $\tilde{f} = c\tilde{f}_j$ for some $c \in k$. This means that $f - cf_j$ is of a lower level than i_j . Part (b) now follows by induction on j . Q.E.D.

Let $\alpha: k\{u_1, \dots, u_l\} \rightarrow M_d(k)$ be as above. We define $\mathcal{W}(\phi, \alpha) \subset \text{Gr}(d, n)$

to be the set of all irreducible subspaces of k^n such that the representation $k\{u_1, \dots, u_l\} \rightarrow \text{End}(U)$ induced by ϕ is isomorphic to α .

7.4 Lemma. *Let n_α be the number of $i = 1, \dots, q$ such that ϕ_i is equivalent to α . Then $W(\phi, \alpha)$ is a projective subvariety of $\text{Gr}(d, n)$ of dimension at most $n_\alpha - 1$.*

Proof. By the definition of the algebraic structure on $\text{Gr}(d, n)$ the map

$$\begin{aligned} \text{Hom}_k(U_\alpha, k^n) &\rightarrow \text{Gr}(d, n) \\ f &\rightarrow f(U_\alpha) \end{aligned}$$

is rational. Denote the restriction of this map to H_α by F . By Lemma 7.1(a) the image of $(0) \neq f \in H_\alpha$ has dimension d , i.e. F is regular on $H_\alpha \setminus (0)$. By Lemma 7.2(c) the image of F is precisely $W(\phi, \alpha)$. By Lemma 7.1(b) $F(f) = F(g)$ if and only if $f = cg$. Hence, F induces an injective regular map

$$\tilde{F}: \mathbf{P}(H_\alpha) \rightarrow \text{Gr}(d, n)$$

whose image $W(\phi, \alpha)$ is a projective subvariety of $\text{Gr}(d, n)$ is a projective subvariety of $\text{Gr}(d, n)$. By Lemma 7.3(b), $\dim_k H_\alpha \leq n_\alpha$. Hence, $\dim W(\phi, \alpha) \leq n_\alpha - 1$. Q.E.D.

7.5 Lemma. *Let $\psi: k\{u_1, \dots, u_s\} \rightarrow M_n(k)$ be a representation such that*

$$\phi(k\{u_1, \dots, u_l\}) \subset \psi(k\{u_1, \dots, u_s\}) \quad \text{and} \quad \tau(\phi) = \tau(\psi).$$

If a subspace $U \subset k^n$ is invariant and irreducible for ψ then it is invariant and irreducible for ϕ .

Proof. U is invariant for ϕ because $\phi(k\{u_1, \dots, u_l\}) \subset \psi(k\{u_1, \dots, u_s\})$. By our assumption on the representation types of ϕ and ψ , if (12) is a composition series for ψ then it is also a composition series for ϕ . Suppose U is of level i as an irreducible representation for ψ . Then the projection map $U \rightarrow V_i/V_{i-1}$ is an isomorphism of $k\{u_1, \dots, u_s\}$ -modules. Consider them as $k\{u_1, \dots, u_l\}$ -modules via ϕ . Since the right-hand side is irreducible, the left-hand side must be irreducible as well. Q.E.D.

8. POLYNOMIAL EQUIVALENCE OF IRREDUCIBLE REPRESENTATIONS

In this section we complete the proof of Theorem 4.4.

We shall think of elements of $M = M_{d_1} \times \dots \times M_{d_r}$ as square block-diagonal matrices of size $d = d_1 + \dots + d_r$, as we did in §6. It will thus make sense to talk about the representation type of a representation

$$\rho = (X_1, \dots, X_s): k\{u_1, \dots, u_s\} \rightarrow M;$$

see 2.5. As usual, it will be denoted by $\tau(\rho)$ or $\tau(X_1, \dots, X_s)$.

If one attempts to reduce Theorem 4.4 to Theorem 4.3 by induction on the representation type of $r(\rho)$, one naturally arrives at the following definition.

An irreducible representation $\rho: k\{u_1, \dots, u_m\} \rightarrow M$ will be called *optimal* if

$$\tau(X_1, X_2) = \max\{\tau(\rho \circ \sigma(u_1), \dots, \rho \circ \sigma(u_{m-1})): \sigma \in \text{Aut}(k\{u_1, \dots, u_m\})\}.$$

8.1 Proposition. *Let $m \geq 3$. Then every irreducible representation of $k\{u_1, \dots, u_m\}$ in M is polynomially equivalent to an optimal representation.*

Proof. Let $\rho = (X_1, \dots, X_m)$ be an irreducible representation of $k\{u_1, \dots, u_m\}$ in M . We may assume without loss of generality that $\mu = \tau(X_1, \dots, X_{m-1})$ is maximal among all representation types $\tau(Y_1, \dots, Y_{m-1})$ where (Y_1, \dots, Y_m) is polynomially equivalent to (X_1, \dots, X_m) .

8.2 Lemma. *Let*

$$l = a_1 u_1 + \dots + a_{m-1} u_{m-1}.$$

There exists a $p \in k\{u_1, \dots, u_{m-1}\}$ such that $\tau(\rho(p), \rho(l)) = \mu$ for a generic choice of the coefficients $a_1, \dots, a_{m-1} \in k$.

Proof. This lemma is a direct consequence of Lemma 6.2(b). Indeed, let

$$\varphi: k\{u_1, \dots, u_m\} \rightarrow N$$

be the reduced semisimple representation associated to $r(\rho) = (X_1, \dots, X_{m-1})$. Choose an element of N with distinct eigenvalues (as a block-diagonal matrix). Since φ is irreducible, we can write this element as $\rho(p)$ for some $p \in k\{u_1, \dots, u_{m-1}\}$. The assertion of the lemma follows from the fact that for a generic choice of $a_1, \dots, a_{m-1} \in k$, $\rho(p)$ and $\rho(l)$ generate N ; see Lemma 6.2(b). Q.E.D.

Choose $p \in k\{u_1, \dots, u_{m-1}\}$ as in Lemma 8.2. We define $\sigma: k\{u_1, \dots, u_m\} \rightarrow k\{u_1, \dots, u_m\}$ by

$$\begin{aligned} u_1 &\rightarrow a_1 u_1 + \dots + a_{m-1} u_{m-1}, \\ u_2 &\rightarrow a_m u_m + p(u_1, \dots, u_{m-1}), \\ u_3 &\rightarrow u_3, \\ &\vdots \\ u_{m-1} &\rightarrow u_{m-1}, \\ u_m &\rightarrow u_2. \end{aligned}$$

We claim that for a generic choice of the coefficients $a_1, \dots, a_m \in k$

$$(13) \quad \tau(\rho \circ \sigma(u_1), \rho \circ \sigma(u_2)) \geq \mu.$$

Indeed, by Corollary 2.8 it is enough to show that (13) holds for one choice of a_1, \dots, a_m . When $a_m = 0$ this follows from Lemma 8.2.

Hence, we can choose the coefficients a_1, \dots, a_i so that (13) holds and $a_1, a_m \neq 0$. The latter condition insures that σ is invertible. Since

$$\mu \leq \tau(\rho \circ \sigma(u_1), \rho \circ \sigma(u_2)) \leq \tau(\rho \circ \sigma(u_1), \dots, \rho \circ \sigma(u_{m-1})) \leq \mu,$$

this completes the proof of Proposition 8.1. Q.E.D.

8.3 Proposition. *Let $m \geq n + 1$, let*

$$\rho = (X_1, \dots, X_m): k\{u_1, \dots, u_m\} \rightarrow M_n(k)$$

be an optimal irreducible representation, and let

$$L: k\{u_1, \dots, u_m\} \rightarrow k\{u_1, \dots, u_m\}$$

be given by

$$(14) \quad \begin{aligned} u_1 &\rightarrow a_{11}u_1 + \cdots + a_{1m}u_m, \\ &\vdots \\ u_{m-1} &\rightarrow a_{m-11}u_1 + \cdots + a_{m-1m}u_m, \\ u_m &\rightarrow u_m. \end{aligned}$$

Then for a generic choice of the coefficients $a_{ij} \in k$ the representation $\rho \circ L$ is saturated.

Proof. Note that it is enough to find one such choice of a_{ij} . For $i = 1, \dots, m$ let $Y_i = a_{i1}X_1 + \cdots + a_{im}X_m$. By Lemma 6.1,

$$(15) \quad \dim \text{Gr}(1, n) \cap V(Y_1, Y_2) \leq n - 3$$

for a generic choice of $a_{11}, \dots, a_{1m}, a_{21}, \dots, a_{2m} \in k$. Note that if $m = 3$ then $n \leq 2$. In this case Y_1 and Y_2 have no common invariant 1-dimensional subspaces in k^n . Hence, they generate $M_n(k)$ which proves the proposition. Thus from now on we may assume that m is at least 4.

Let $\mu = \tau(X_1, X_2) = \tau(X_1, \dots, X_{m-1})$. For a generic choice of $a_{11}, \dots, a_{1m}, a_{21}, \dots, a_{2m} \in k$ we also have $\tau(Y_1, Y_2) \geq \mu$; see Corollary 2.8. Since ρ is optimal, this is the same as

$$(16) \quad \tau(Y_1, Y_2) = \mu.$$

We fix $a_{11}, \dots, a_{1m}, a_{21}, \dots, a_{2m} \in k$ so that (15) and (16) hold.

Let $\phi = (Y_1, Y_2): k\{u_1, u_2\} \rightarrow M_d(k)$ and let

$$(0) = V_0 \subset V_1 \subset \cdots \subset V_q = V$$

be a composition series for ϕ . Denote the irreducible representation $k\{u_1, u_2\} \rightarrow \text{End}(V_i/V_{i-1})$ by ϕ_i , as we did in §7.

Recall that in the previous section we defined $W(\phi, \phi_i)$ as the set of all ϕ -irreducible $U \subset k^n$ such that the induced representation $k\{u_1, u_2\} \rightarrow \text{End}(U)$ is equivalent to ϕ_i . We define $W \subset \text{Gr}(n)$ to be the union of all $W(\phi, \phi_i)$ with $\dim V_i/V_{i-1} \geq 2$. By Lemma 7.4 $\dim W(\phi, \phi_i) \leq n_{\phi_i} - 1$ where n_{ϕ_i} is the number of $j = 1, \dots, q$ such that ϕ_j is equivalent to ϕ_i . If the $\dim V_i/V_{i-1}$ is at least 2 then $n_{\phi_i} \leq [n/2]$. Hence,

$$\dim W(\phi, \phi_i) \leq n_{\phi_i} - 1 \leq \left\lfloor \frac{n}{2} \right\rfloor - 1 \leq \left\lfloor \frac{m-1}{2} \right\rfloor - 1 \leq m - 4.$$

Therefore, $\dim W \leq m - 4$. Let $W_1 = \text{Gr}(1, n) \cap V(Y_1, Y_2)$. By (15) $\dim W_1 \leq n - 3 \leq m - 4$.

By Proposition 6.1,

$$W \cap V(Y_3, \dots, Y_{m-1}) = \emptyset \quad \text{and} \quad W_1 \cap V(Y_3, \dots, Y_{m-1}) = \emptyset$$

for a generic choice of a_{ij} with $i = 3, \dots, m-1$ and $j = 1, \dots, m$. In order to prove Proposition 8.3 it is enough to show that for any such choice of a_{ij} Y_1, \dots, Y_{m-1} generate the matrix algebra $M_n(k)$.

Indeed, assume the contrary. Then (Y_1, \dots, Y_{m-1}) will have an irreducible invariant subspace $U \subset k^n$. This subspace cannot be 1-dimensional, since $\text{Gr}(1, n) \cap V(Y_1, \dots, Y_{m-1}) = \emptyset$. By our choice of Y_1 and Y_2 ,

$$\tau(Y_1, Y_2) = \tau(Y_1, \dots, Y_{m-1}) = \mu.$$

Hence, by Lemma 7.5 U will be invariant and irreducible for $\phi = (Y_1, Y_2)$. By Lemma 7.2(b) this implies $U \in W$, contradicting $W \cap V(V_3, \dots, V_{m-1}) = \emptyset$. \square

We can now complete the proof of Theorem 4.4. Let $M = M_{d_1} \times \dots \times M_{d_r}$ and let

$$\rho = \rho_1 \oplus \dots \oplus \rho_r: k\{u_1, \dots, u_m\} \rightarrow M$$

be an irreducible representation. Here $\rho_i: k\{u_1, \dots, u_m\} \rightarrow M_{d_i}$ for $i = 1, \dots, r$. The representations ρ_i are irreducible and pairwise inequivalent. Recall that in view of Proposition 3.3 we are assuming that $m \geq 3$. Hence, it is enough to show that ρ is polynomially equivalent to a saturated representation; then Theorem 4.3 will apply.

Let $L: k\{u_1, \dots, u_m\} \rightarrow k\{u_1, \dots, u_m\}$ be as in (14). Then the following conditions are satisfied for a generic choice of the coefficients a_{ij} .

- (i) $\det(a_{ij}) \neq 0$, i.e. L is an automorphism of $k\{u_1, \dots, u_m\}$.
- (ii) The representations $\rho_1 \circ L, \dots, \rho_r \circ L$ are saturated. Since

$$m \geq \max\{d_1, \dots, d_r\} + 1,$$

this follows from Proposition 8.3.

- (iii) The representations $\rho_1 \circ L, \dots, \rho_r \circ L$ are pairwise inequivalent.

By Proposition 5.1 $\rho \circ L$ is polynomially equivalent to a saturated representation. This completes the proof of Theorem 4.4.

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